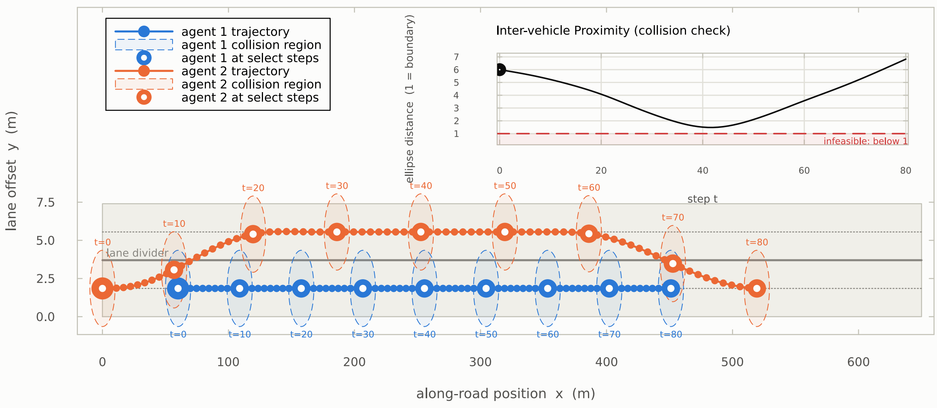
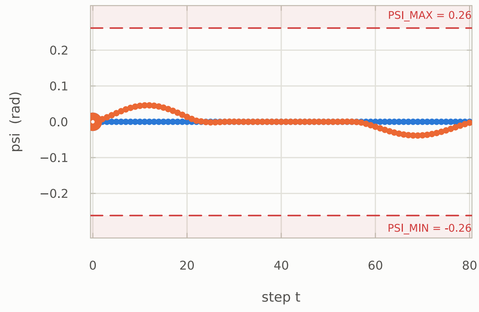
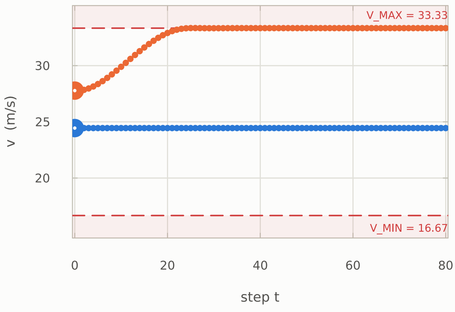
A. Bird's-eye view [polish-eta1e-04, rho=1e-10]



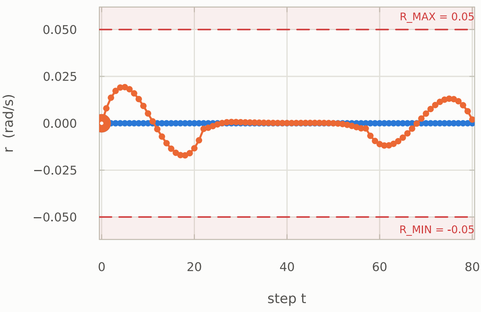
B. Heading



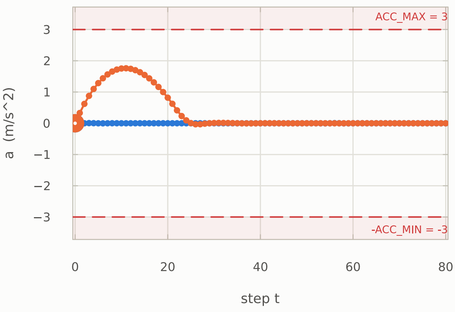
C. Speed



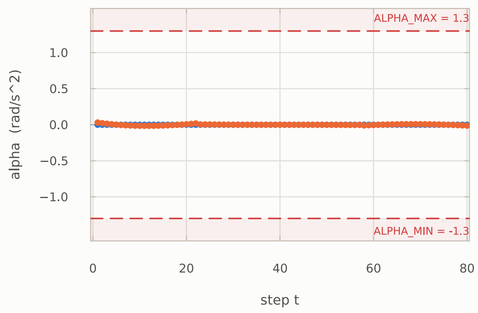
D1. Yaw rate



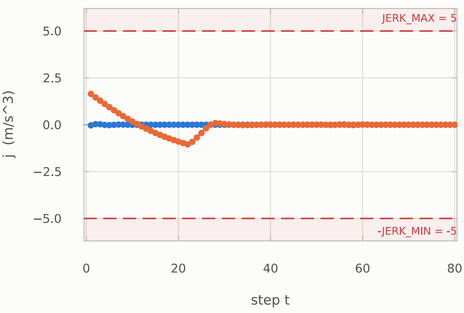
D2. Longitudinal acceleration



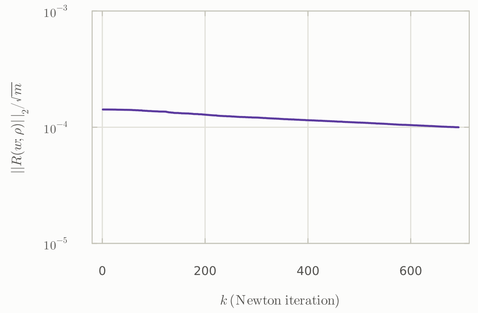
E1. Yaw acceleration



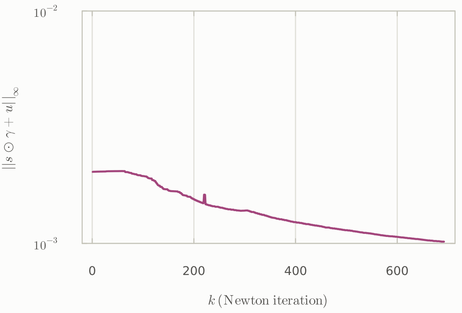
E2. Longitudinal jerk



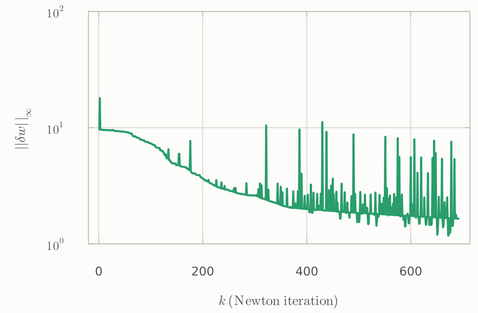
F. Homotopy residual (RMS) [||K_0||/sqrt(m) < 1e-04]



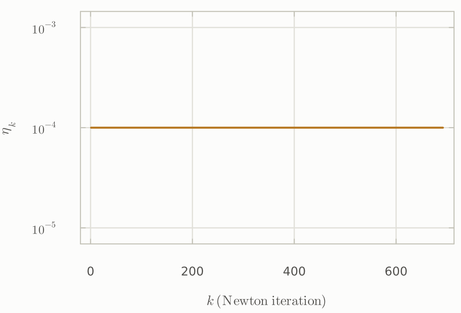
G. Complementarity slackness



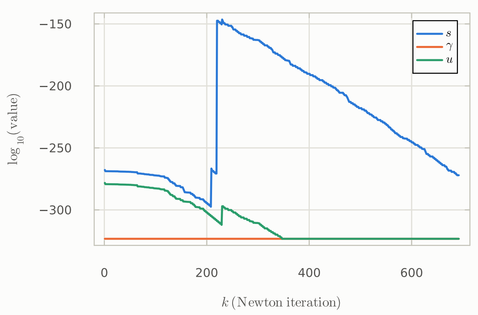
H. Newton direction size [no step at k = 693]



I. Tikhonov regularization



J. Smallest positive coordinates



K. Newton step size

